Graphs

Application

- Airline Scheduling
- Search Engine Algorithms
- Social Media Marketing
- Design Computer Chips

Introduction to Graphs

Definition: A **simple graph** G = (V, E) consists of V, a nonempty set of vertices, and E, a set of **unordered pairs** of distinct elements of V called edges.

For each $e \in E$, $e = \{u, v\}$ where $u, v \in V$.

An undirected graph (not simple) may contain loops. An edge e is a loop if $e = \{u, u\}$ for some $u \in V$.

Definition: A **directed graph** G = (V, E) consists of a set V of vertices and a set E of edges that are ordered pairs of elements in V.

For each $e \in E$, e = (u, v) where u, v $\in$ V.

An edge e is a loop if e = (u, u) for some $u \in V$.

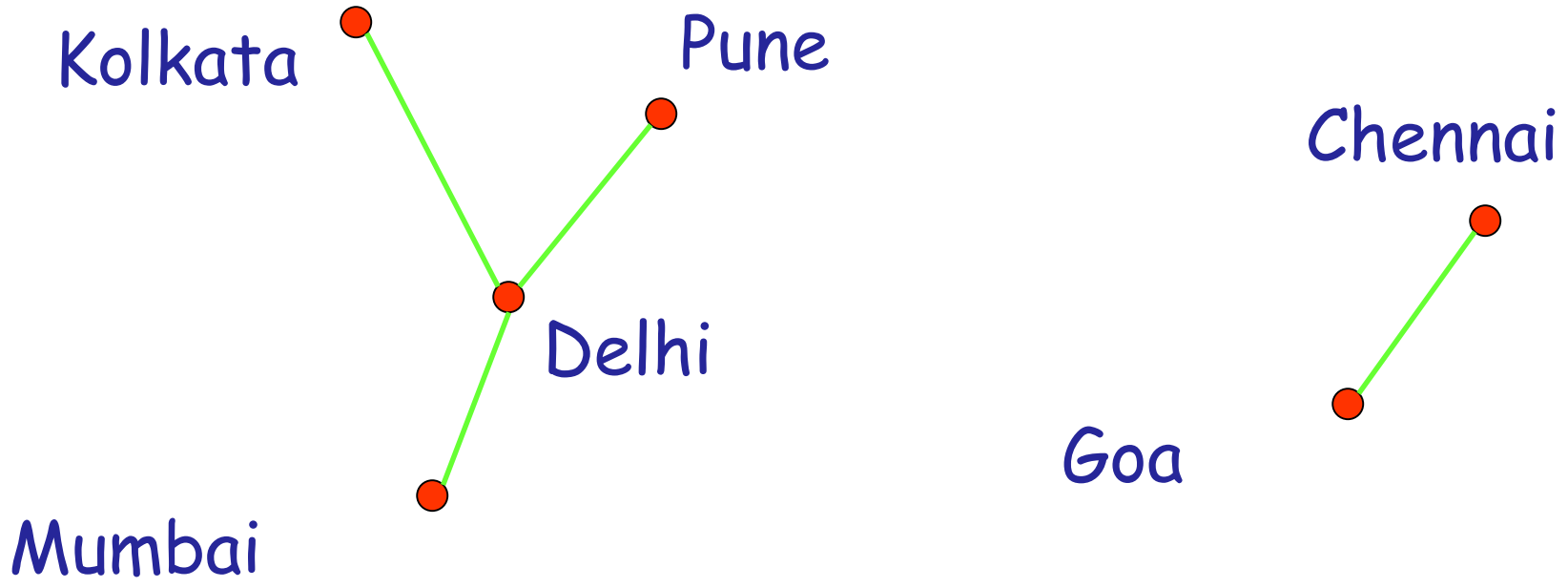
A simple graph is just like a directed graph, but with no specified direction of its edges.

Broadcast and satellite TV / radio are one-way connections from the broadcaster to your antenna.

Graph Models

Example I: How can we represent a network of (bi-directional) railways connecting a set of cities?

We should use a **simple graph** with an edge {a, b} indicating a direct train connection between cities a and b.



A graph of Facebook friends is a simple graph. It does not have multiple edges, since you're either friends or you're not. Also, you cannot be your own Facebook friend, so no loops

Graph Terminology

Definition: Two vertices u and v in an undirected graph G are called **adjacent** (or **neighbors**) in G if {u, v} is an edge in G.

If e = {u, v}, the edge e is called **incident with** the vertices u and v. The edge e is also said to **connect** u and v.

The vertices u and v are called **endpoints** of the edge {u, v}.

Graph Terminology

Definition: The **degree** of a vertex in an undirected graph is the number of edges incident with it, except that a loop at a vertex contributes twice to the degree of that vertex.

In other words, you can determine the degree of a vertex in a displayed graph by **counting the lines** that touch it.

The degree of the vertex v is denoted by **deg(v).**

Graph Terminology

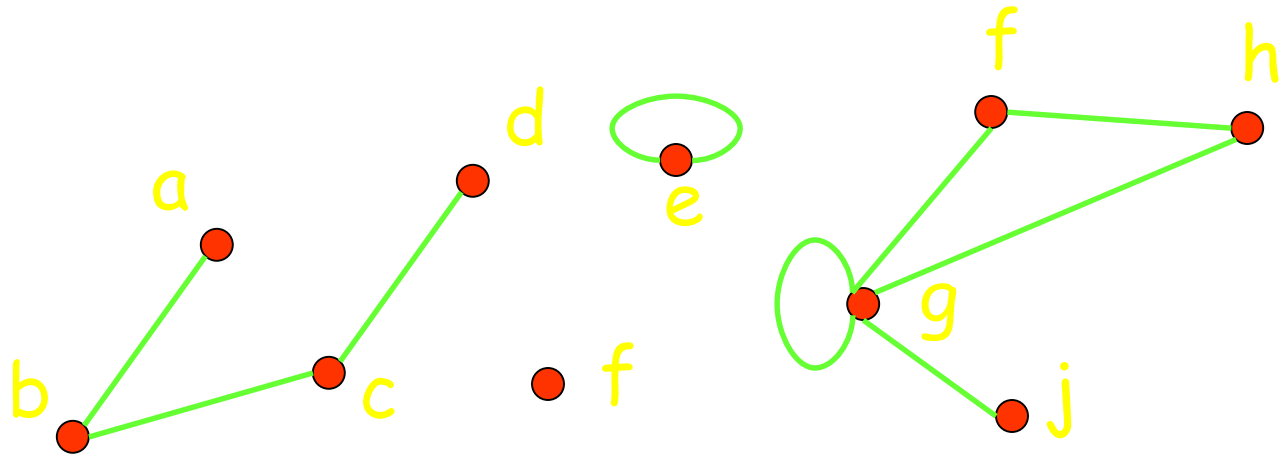
A vertex of degree 0 is called **isolated**, since it is not adjacent to any vertex.

Note: A vertex with a **loop** at it has at least degree 2 and, by definition, is **not isolated**, even if it is not adjacent to any **other** vertex.

A vertex of degree 1 is called **pendant**. It is adjacent to exactly one other vertex.

Graph Terminology

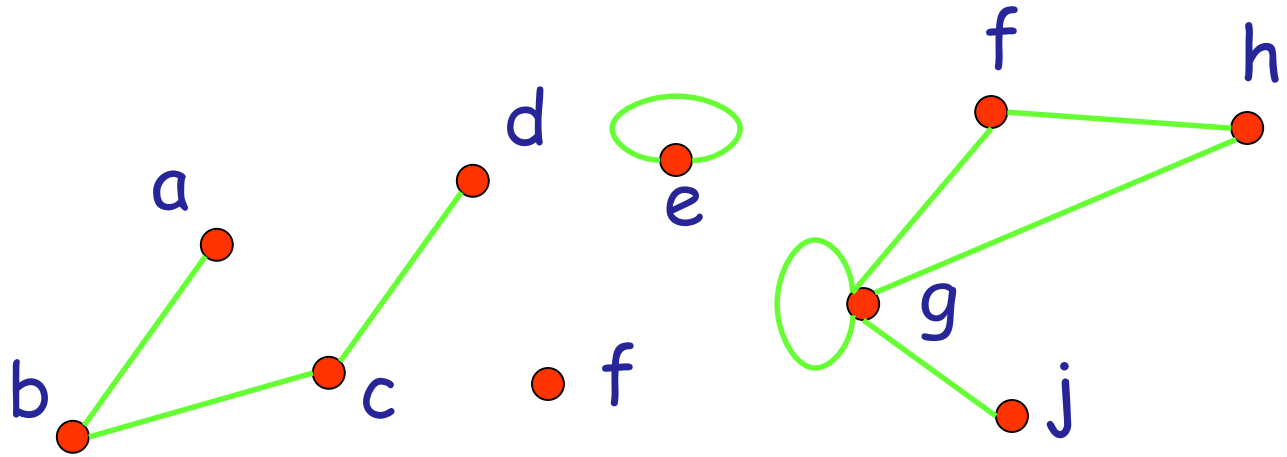
Example: Which vertices in the following graph are isolated, which are pendant, and what is the maximum degree? What type of graph is it?



Solution: Vertex f is isolated, and vertices a, d and j are pendant. The maximum degree is deg(g) = 5.
This graph is a pseudograph (undirected, loops).

Graph Terminology

Let us look at the same graph again and determine the number of its edges and the sum of the degrees of all its vertices:



Result: There are 9 edges, and the sum of all degrees is 18. This is easy to explain: Each new edge increases the sum of degrees by exactly two.

Graph Terminology

Leonhard Euler

The Handshaking Theorem: Let G = (V, E) be an undirected graph with e edges. Then

$2e = \sum_{v \in V} \deg(v)$

Example: How many edges are there in a graph with 10 vertices, each of degree 6?

Solution: The sum of the degrees of the vertices is $6 \cdot 10 = 60$. According to the Handshaking Theorem, it follows that $2e = 60$, so there are 30 edges.

Graph Terminology

Theorem: An undirected graph has an even number of vertices of odd degree.

Proof: Let V1 and V2 be the set of vertices of even and odd degrees, respectively (Thus $V1 \cap V2 = \varnothing$, and $V1 \cup V2 = V$).

Then by Handshaking theorem

$$2|E| = \sum_{v \in V} \deg(v) = \sum_{v \in V1} \deg(v) + \sum_{v \in V2} \deg(v)$$

Since both $2|E|$ and $\sum_{v \in V1} \deg(v)$ are even,

$\sum_{v \in V2} \deg(v)$ must be even.

Since deg(v) if odd for all $v \in V2$, $|V2|$ must be even.

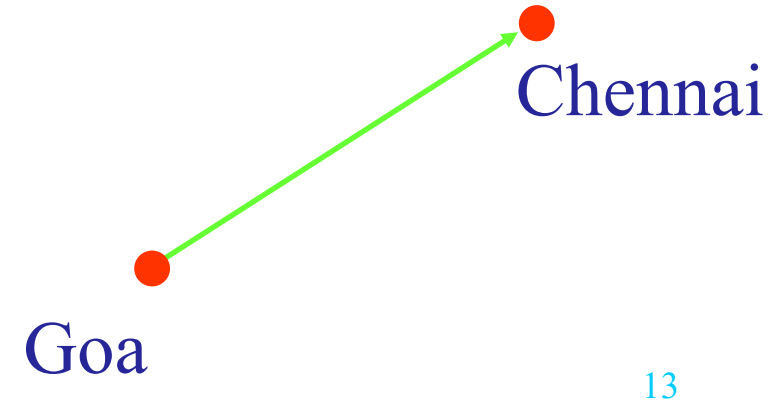
QED (https://en.wikipedia.org/wiki/Q.E.D.)

Graph Terminology

Definition: When (u, v) is an edge of the graph G with directed edges, u is said to be **adjacent to** v, and v is said to be **adjacent from** u.

The vertex u is called the **initial vertex** of (u, v), and v is called the **terminal vertex** of (u, v).

The initial vertex and terminal vertex of a loop are the same.



Graph Terminology

Definition: In a graph with directed edges, the **in-degree** of a vertex v, denoted by $\mathbf{deg^-(v)}$, is the number of edges with v as their **terminal vertex**.

The **out-degree** of v, denoted by $\mathbf{deg^+(v)}$, is the number of edges with v as their initial vertex.

Question: How does adding a loop to a vertex change the in-degree and out-degree of that vertex?

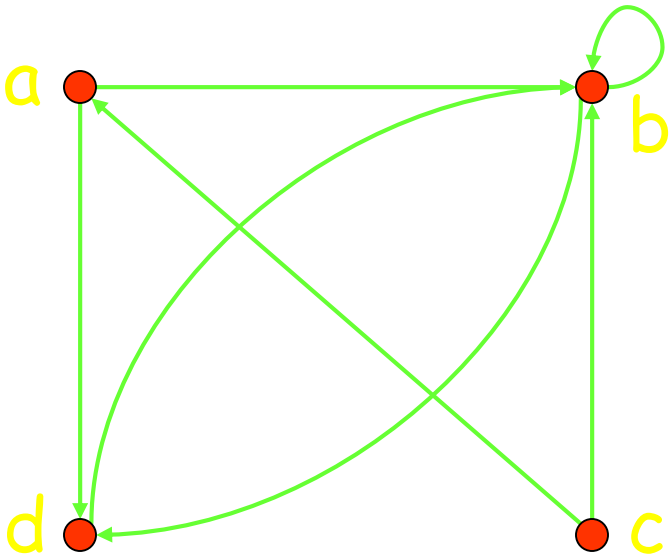
Answer: It increases both the in-degree and the out-degree by one.

Graph Terminology

Example: What are the in-degrees and out-degrees of the vertices a, b, c, d in this graph:

$\deg^-(a) = 1$

$\deg^+(a) = 2$



$\deg^-(b) = 4$

$\deg^+(b) = 2$

$\deg^-(d) = 2$

$\deg^+(d) = 1$

$\deg^-(c) = 0$

$\deg^+(c) = 2$

Graph Terminology

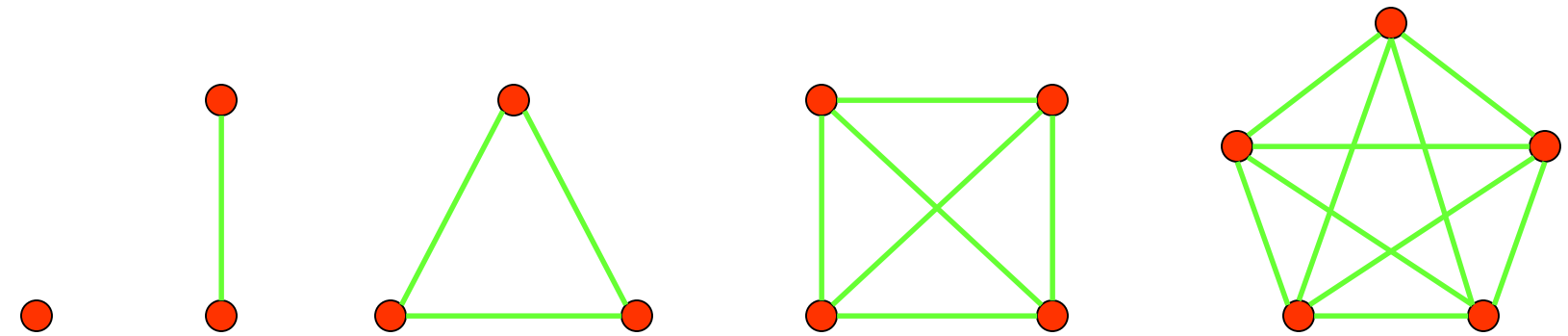
Theorem: Let G = (V, E) be a graph with directed edges. Then:

$\sum_{v \in V} \deg^-(v) = \sum_{v \in V} \deg^+(v) = |E|$

This is easy to see, because every new edge increases both the sum of in-degrees and the sum of out-degrees by one.

Special Graphs

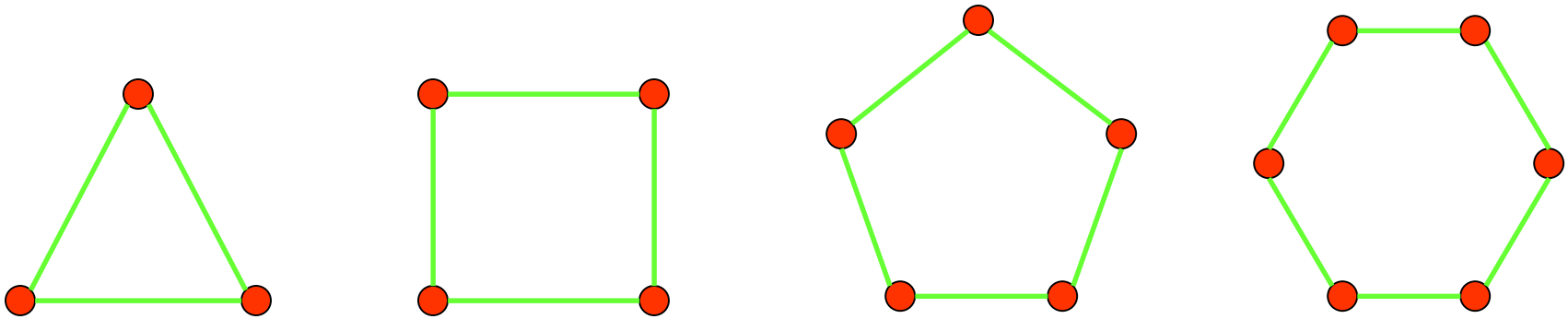
Definition: The **complete graph** on n vertices, denoted by K_n, is the simple graph that contains exactly one edge between each pair of distinct vertices.



K_1 K_2 K_3 K_4 K_5

Special Graphs

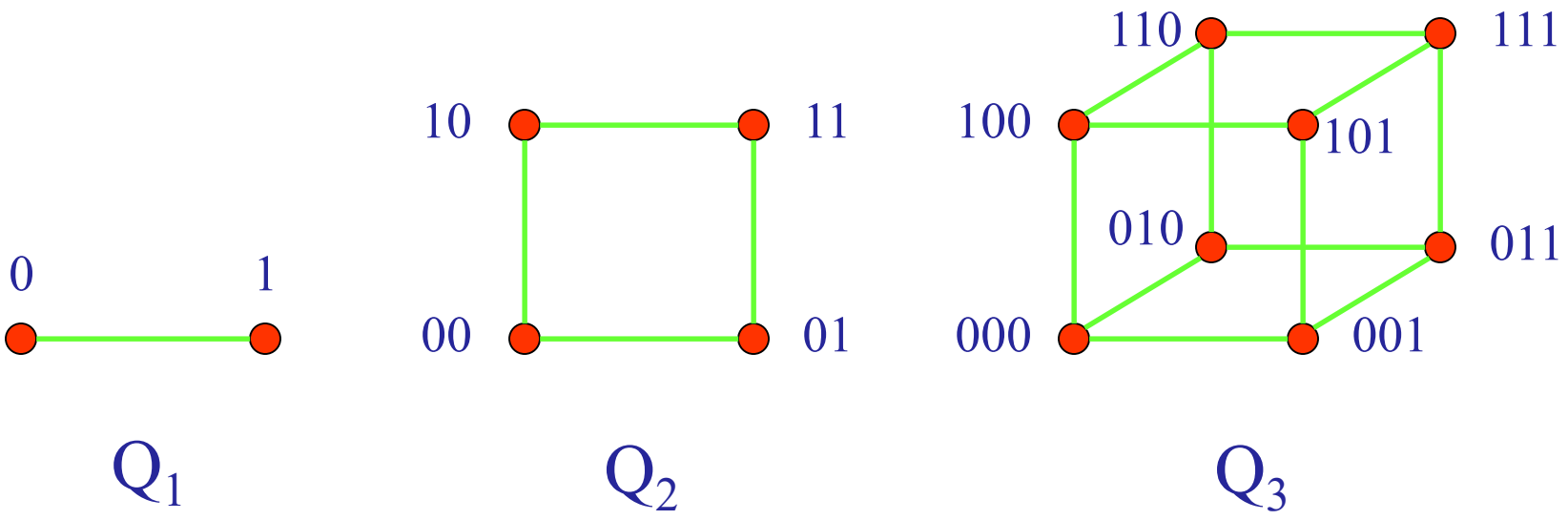
Definition: The **cycle** C_n, $n \geq 3$, consists of n vertices v_1, v_2, …, v_n and edges $\{v_1, v_2\}$, $\{v_2, v_3\}$, …, $\{v_{n-1}, v_n\}$, $\{v_n, v_1\}$.



C_3 C_4 C_5 C_6

Special Graphs

Definition: The **n-cube,** denoted by Q_n, is the graph that has vertices representing the 2^n bit strings of length n. Two vertices are adjacent if and only if the bit strings that they represent differ in exactly one bit position.



Special Graphs

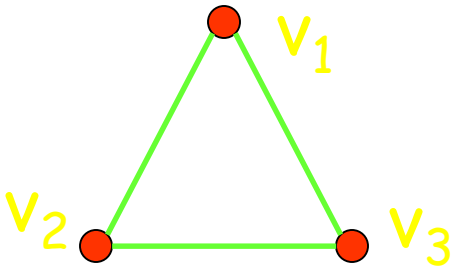
Definition: A simple graph is called **bipartite** if its vertex set V can be partitioned into two disjoint nonempty sets V_1 and V_2 such that every edge in the graph connects a vertex in V_1 with a vertex in V_2 (so that no edge in G connects either two vertices in V_1 or two vertices in V_2).

For example, consider a graph that represents each person in a village by a vertex and each marriage by an edge.

This graph is **bipartite** because each edge connects a vertex in the **subset of males** with a vertex in the **subset of females** (if we think of traditional marriages)!!!!.

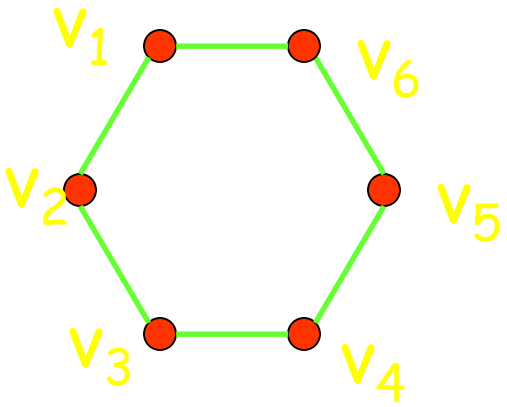
Special Graphs

Example I: Is C_3 bipartite?

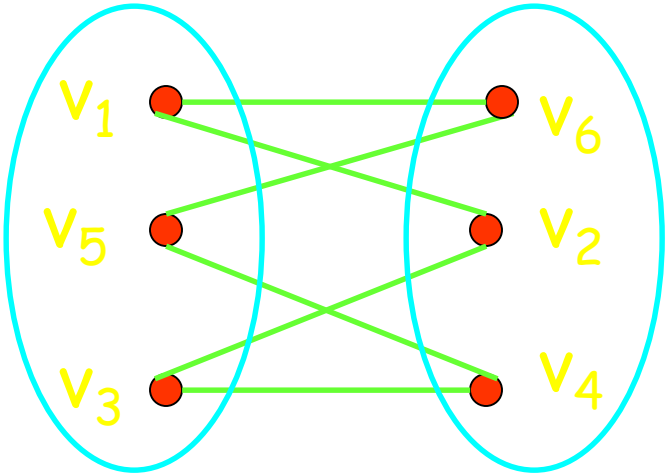


No, because there is no way to partition the vertices into two sets so that there are no edges with both endpoints in the same set.

Example II: Is C_6 bipartite?

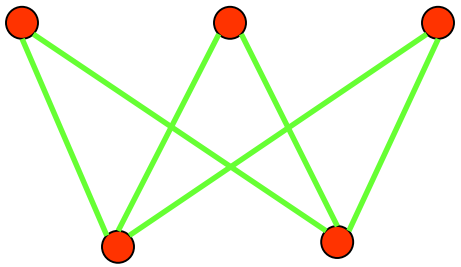


Yes, because we can display C_6 like this:

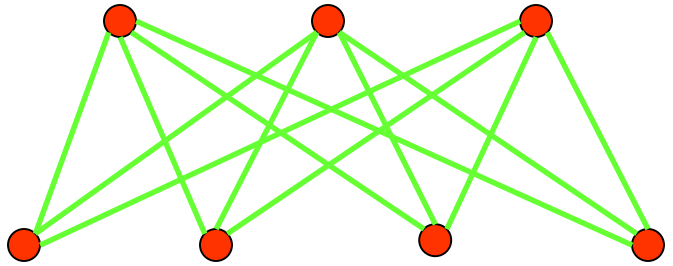


Special Graphs

Definition: The **complete bipartite graph** $K_{m,n}$ is the graph that has its vertex set partitioned into two subsets of m and n vertices, respectively. Two vertices are connected if and only if they are in different subsets.



$K_{3,2}$



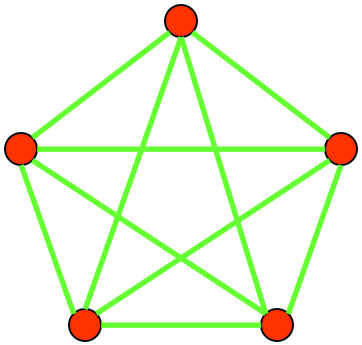
$K_{3,4}$

Operations on Graphs

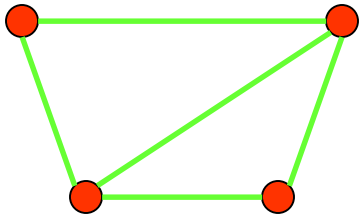
Definition: A **subgraph** of a graph G = (V, E) is a graph H = (W, F) where $W \subseteq V$ and $F \subseteq E$.

Note: Of course, H is a valid graph, so we cannot remove any endpoints of remaining edges when creating H.

Example:



K_5

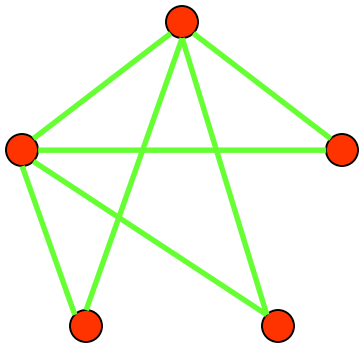


subgraph of K_5

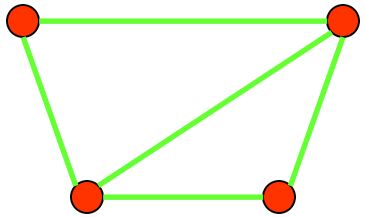
Operations on Graphs

Definition: The **union** of two simple graphs $G_1 = (V_1, E_1)$ and $G_2 = (V_2, E_2)$ is the simple graph with vertex set $V_1 \cup V_2$ and edge set $E_1 \cup E_2$.

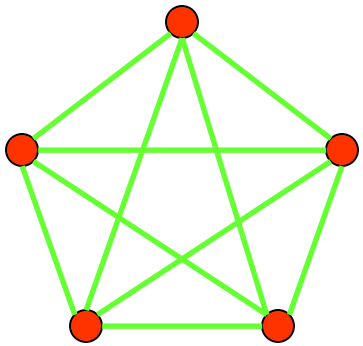
The union of G_1 and G_2 is denoted by $\mathbf{G_1 \cup G_2}$.



G_1

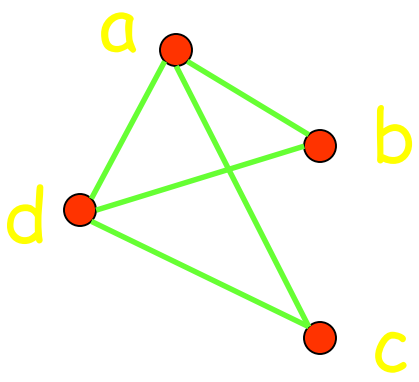


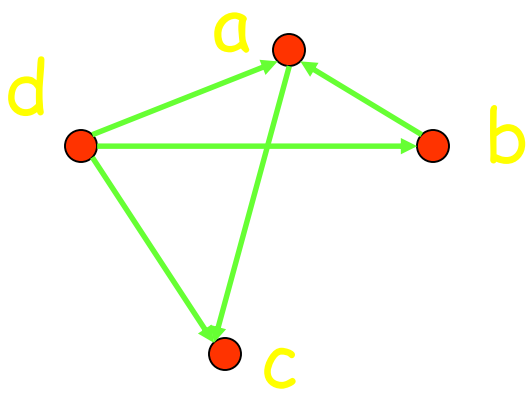
G_2



$G_1 \cup G_2 = K_5$

Representing Graphs





Vertex	Adjacent Vertices
a	b, c, d
b	a, d
c	a, d
d	a, b, c

Initial Vertex	Terminal Vertices
a	c
b	a
c	
d	a, b, c

Representing Graphs

Definition: Let G = (V, E) be a simple graph with |V| = n. Suppose that the vertices of G are listed in arbitrary order as $v_1, v_2, \ldots, v_n$.

The **adjacency matrix** A (or A_G) of G, with respect to this listing of the vertices, is the n×n zero-one matrix with 1 as its (i, j)th entry when v_i and v_j are adjacent, and 0 otherwise.

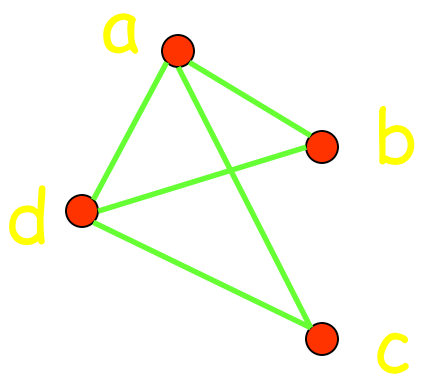
In other words, for an adjacency matrix $A = [a_{ij}]$,

$a_{ij} = 1$ if $\{v_i, v_j\}$ is an edge of G,
$a_{ij} = 0$ otherwise.

A symmetric matrix

Representing Graphs

Example: What is the adjacency matrix A_G for the following graph G based on the order of vertices a, b, c, d ?



Solution:

$$A_G = \begin{bmatrix} 0 & 1 & 1 & 1 \\ 1 & 0 & 0 & 1 \\ 1 & 0 & 0 & 1 \\ 1 & 1 & 1 & 0 \end{bmatrix}$$

Note: Adjacency matrices of undirected graphs are always symmetric.

Representing Graphs

Definition: Let G = (V, E) be an undirected graph with |V| = n. Suppose that the vertices and edges of G are listed in arbitrary order as $v_1, v_2, \ldots, v_n$ and $e_1, e_2, \ldots, e_m$, respectively.

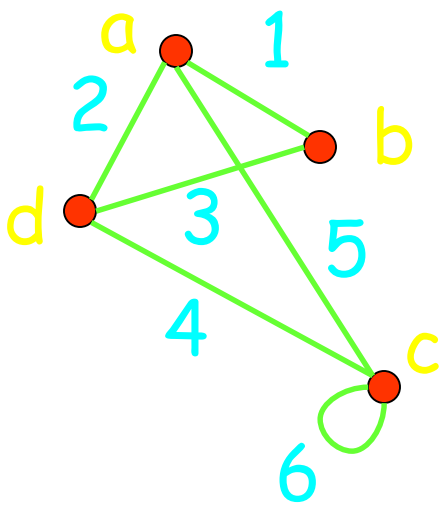
The **incidence matrix** of G with respect to this listing of the vertices and edges is the n×m zero-one matrix with 1 as its (i, j)th entry when edge e_j is incident with v_i, and 0 otherwise.

In other words, for an incidence matrix $M = [m_{ij}]$,

$m_{ij} = 1$ if edge e_j is incident with v_i
$m_{ij} = 0$ otherwise.

Representing Graphs

Example: What is the incidence matrix M for the following graph G based on the order of vertices a, b, c, d and edges 1, 2, 3, 4, 5, 6?



Solution:

$$M = \begin{bmatrix} 1 & 1 & 0 & 0 & 1 & 0 \\ 1 & 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 & 1 & 1 \\ 0 & 1 & 1 & 1 & 0 & 0 \end{bmatrix}$$

Note: Incidence matrices of directed graphs contain two 1s per column for edges connecting two vertices and one 1 per column for loops.

Isomorphism of Graphs

Definition: The simple graphs $G_1 = (V_1, E_1)$ and $G_2 = (V_2, E_2)$ are **isomorphic** if there is a bijection (an one-to-one and onto function) f from V_1 to V_2 with the property that a and b are adjacent in G_1 if and only if f(a) and f(b) are adjacent in G_2, for all a and b in V_1.

Such a function f is called an **isomorphism**.

In other words, G_1 and G_2 are isomorphic if their vertices can be ordered in such a way that the adjacency matrices M_{G_1} and M_{G_2} are identical.

Isomorphism of Graphs

From a visual standpoint, G_1 and G_2 are isomorphic if they can be arranged in such a way that their **displays are identical** (of course without changing adjacency).

Unfortunately, for two simple graphs, each with n vertices, there are **n! possible isomorphisms** that we have to check in order to show that these graphs are isomorphic.

However, showing that two graphs are **not** isomorphic can be easy.

Isomorphism of Graphs

For this purpose we can check **invariants**, that is, properties that two isomorphic simple graphs must both have.

For example, they must have

- the same number of vertices,
- the same number of edges, and
- the same degrees of vertices.

Note that two graphs that **differ** in any of these invariants are not isomorphic, but two graphs that **match** in all of them are not necessarily isomorphic.

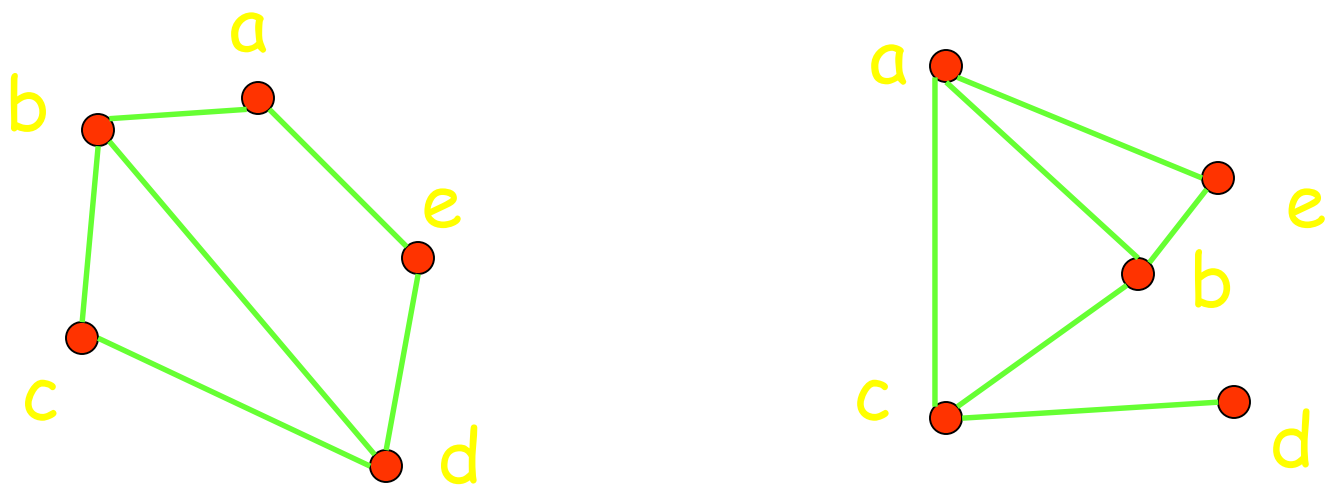
Isomorphism of Graphs

Example I: Are the following two graphs isomorphic?

Solution: Yes, they are isomorphic, because they can be arranged to look identical. You can see this if in the right graph you move vertex b to the left of the edge {a, c}. Then the isomorphism f from the left to the right graph is: f(a) = e, f(b) = a,
f(c) = b, f(d) = c, f(e) = d.

Isomorphism of Graphs

Example II: How about these two graphs?



Solution: No, they are not isomorphic, because they differ in the degrees of their vertices.

Vertex d in right graph is of degree one, but there is no such vertex in the left graph.

Connectivity

Definition: A **path** of length n from u to v, where n is a positive integer, in an **undirected graph** is a sequence of edges $e_1, e_2, \ldots, e_n$ of the graph such that $e_1 = \{x_0, x_1\}$, $e_2 = \{x_1, x_2\}, \ldots, e_n = \{x_{n-1}, x_n\}$, where $x_0 = u$ and $x_n = v$.

When the graph is simple, we denote this path by its **vertex sequence** $x_0, x_1, \ldots, x_n$, since it uniquely determines the path.

The path is a **circuit** if it begins and ends at the same vertex, that is, if $u = v$.

Connectivity

Definition (continued): The path or circuit is said to **pass through** or traverse $x_1, x_2, \ldots, x_{n-1}$.

A path or circuit is **simple** if it does not contain the same edge more than once.

Connectivity

Let us now look at something new:

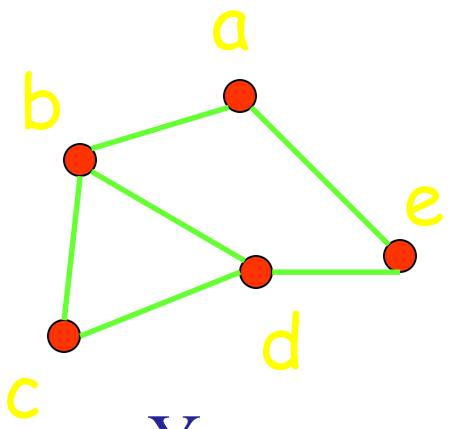
Definition: An undirected graph is called **connected** if there is a path between every pair of distinct vertices in the graph.

For example, any two computers in a network can communicate if and only if the graph of this network is connected.

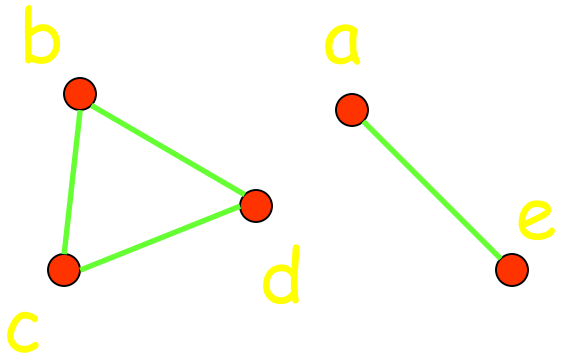
Note: A graph consisting of only one vertex is always connected, because it does not contain any pair of distinct vertices.

Connectivity

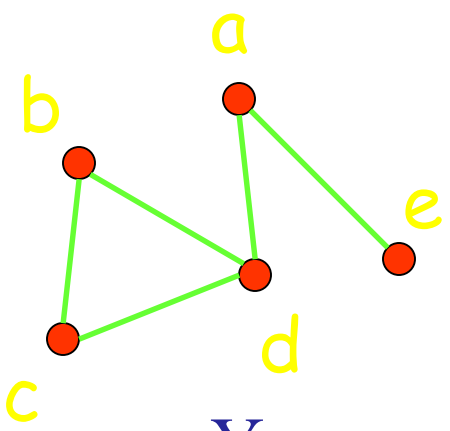
Example: Are the following graphs connected?



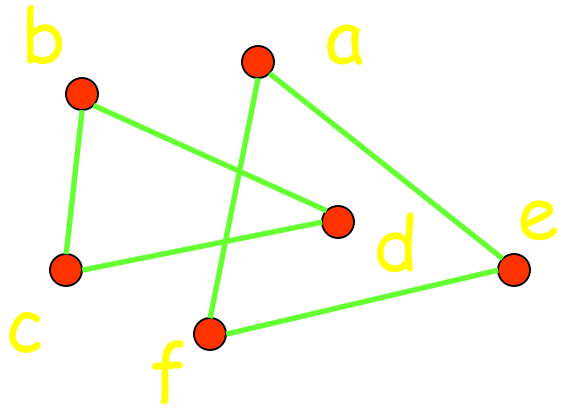
Yes.



No.



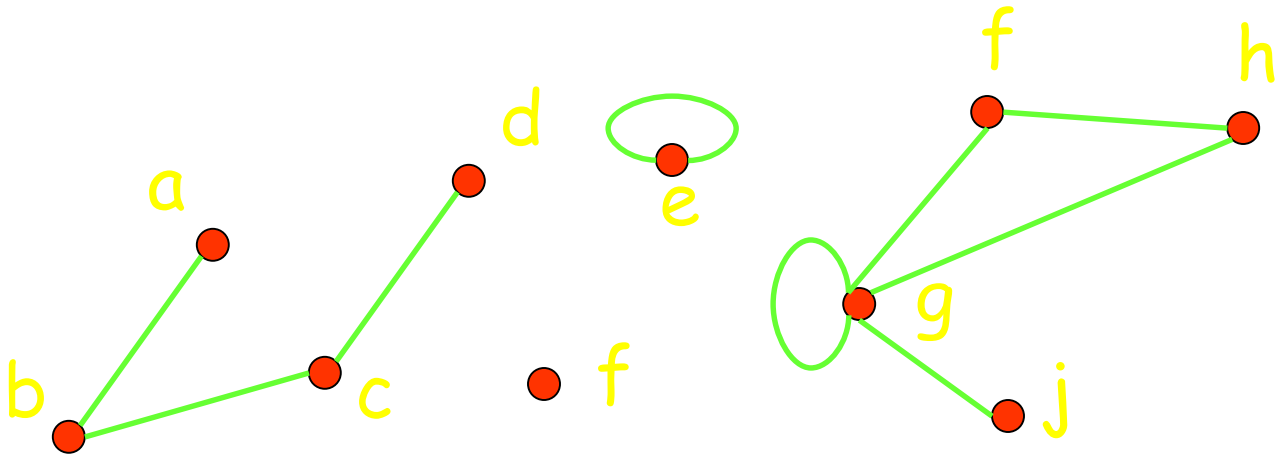
Yes.



No.

Connectivity

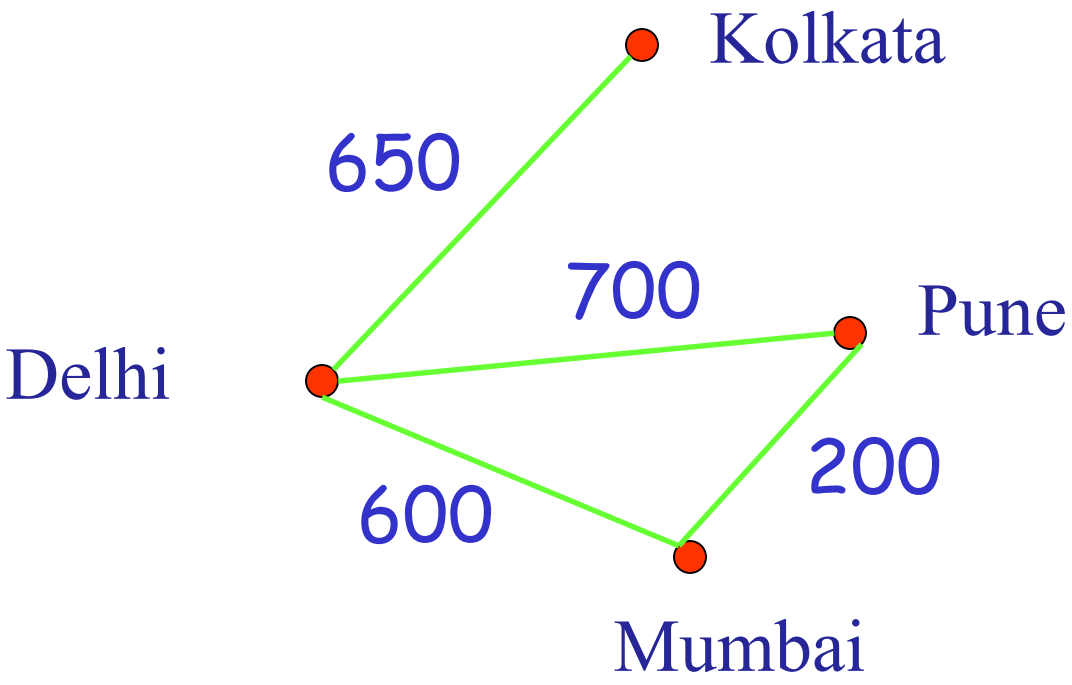
Example: What are the connected components in the following graph?



Solution: The connected components are the graphs with vertices {a, b, c, d}, {e}, {f}, {f, g, h, j}.

Shortest Path Problems

We can assign weights to the edges of graphs, for example to represent the distance between cities in a railway network:



Shortest Path Problems

Such weighted graphs can also be used to model computer networks with response times or costs as weights.

One of the most interesting questions that we can investigate with such graphs is:

What is the **shortest path** between two vertices in the graph, that is, the path with the **minimal sum of weights** along the way?

This corresponds to the shortest train connection or the fastest connection in a computer network.

Dijkstra's Algorithm

Dijkstra's algorithm is an iterative procedure that finds the shortest path between to vertices a and z in a weighted graph.

It proceeds by finding the length of the shortest path from a to successive vertices and adding these vertices to a distinguished set of vertices S.

The algorithm terminates once it reaches the vertex z.

The Traveling Salesman Problem

The **traveling salesman problem** is one of the classical problems in computer science.

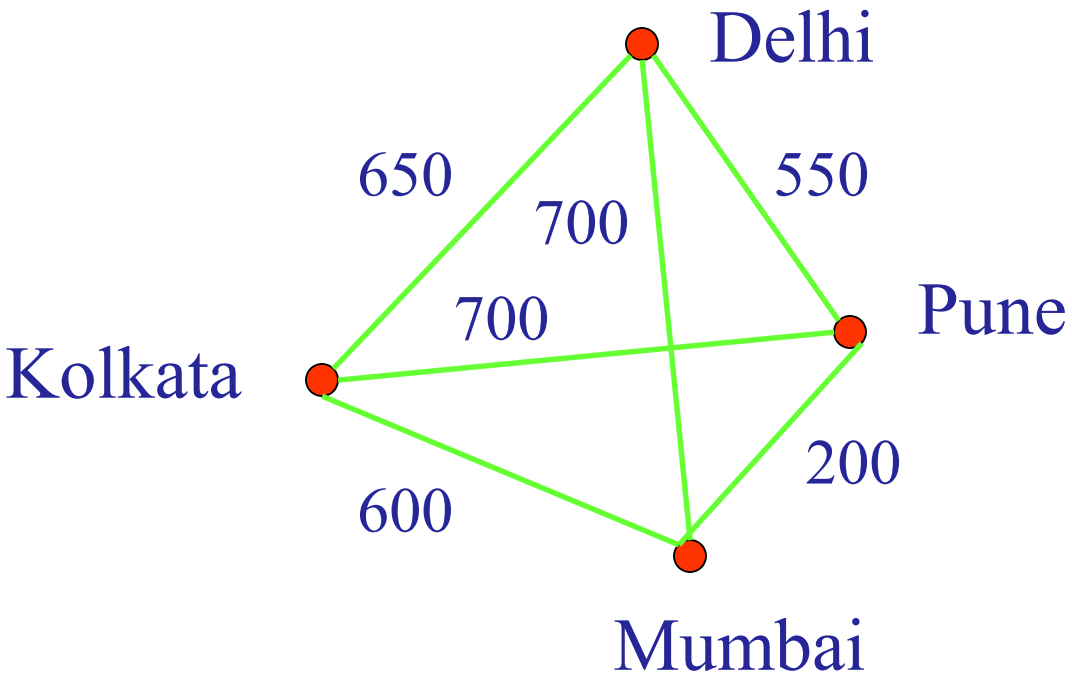
A traveling salesman wants to visit a number of cities and then return to his starting point. Of course he wants to save time and energy, so he wants to determine the **shortest path** for his trip.

We can represent the cities and the distances between them by a weighted, complete, undirected graph.

The problem then is to find the **circuit of minimum total weight that visits each vertex exactly one**.

The Traveling Salesman Problem

Example: What path would the traveling salesman take to visit the following cities?



Solution: The shortest path is 2,000 kms.

The Traveling Salesman Problem

Question: Given n vertices, how many different cycles C_n can we form by connecting these vertices with edges?

Solution: We first choose a starting point. Then we have (n – 1) choices for the second vertex in the cycle, (n – 2) for the third one, and so on, so there are (n – 1)! choices for the whole cycle.

However, this number includes identical cycles that were constructed in **opposite directions**. Therefore, the actual number of different cycles C_n is **(n – 1)!/2**.

The Traveling Salesman Problem

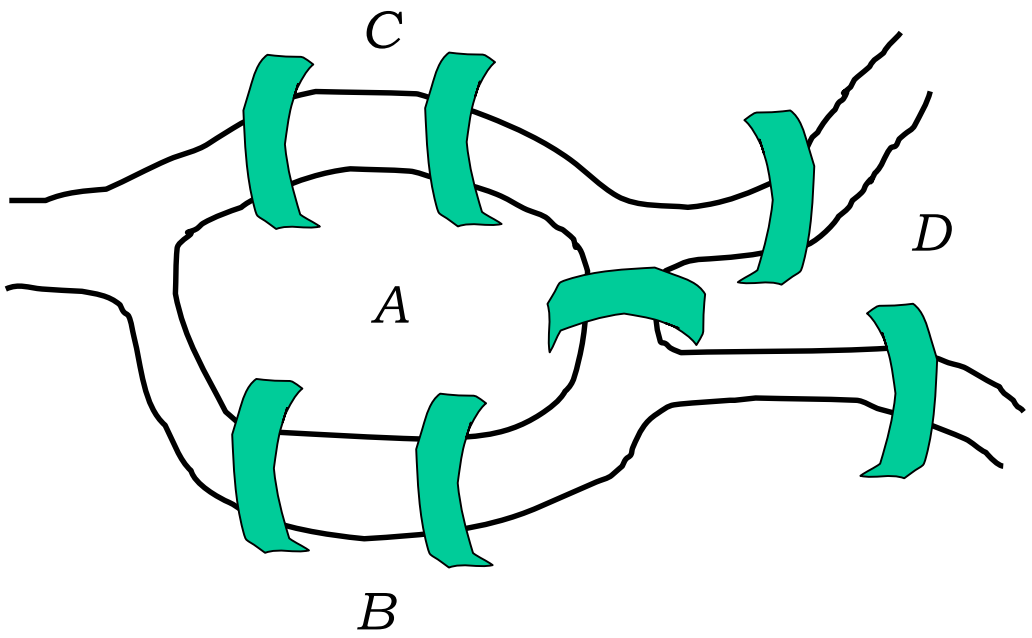
Unfortunately, no algorithm solving the traveling salesman problem with polynomial worst-case time complexity has been devised yet.

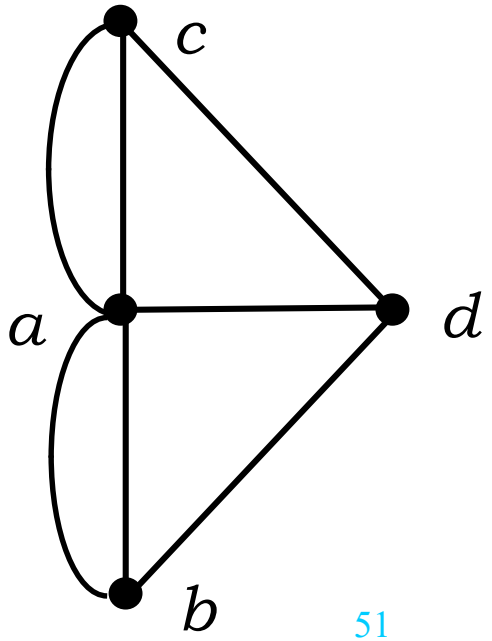
This means that for large numbers of vertices, solving the traveling salesman problem is impractical.

In these cases, we can use efficient **approximation algorithms** that determine a path whose length may be slightly larger than the traveling salesman's path, but

Euler Paths

The Seven bridges of Königsberg



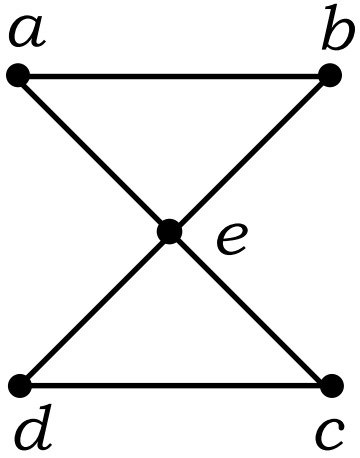


Properties

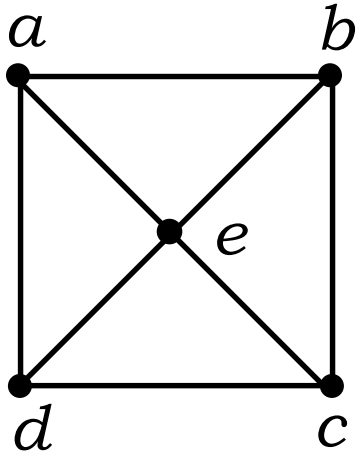
An *Euler path* is a path using every edge of the graph *G* exactly once.

An *Euler circuit* is an Euler path that returns to its start.

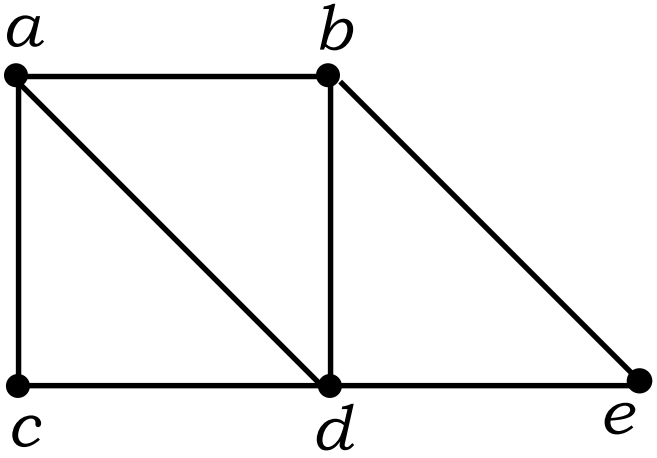
Which of the following graphs has an Euler *circuit*?



yes



no



no

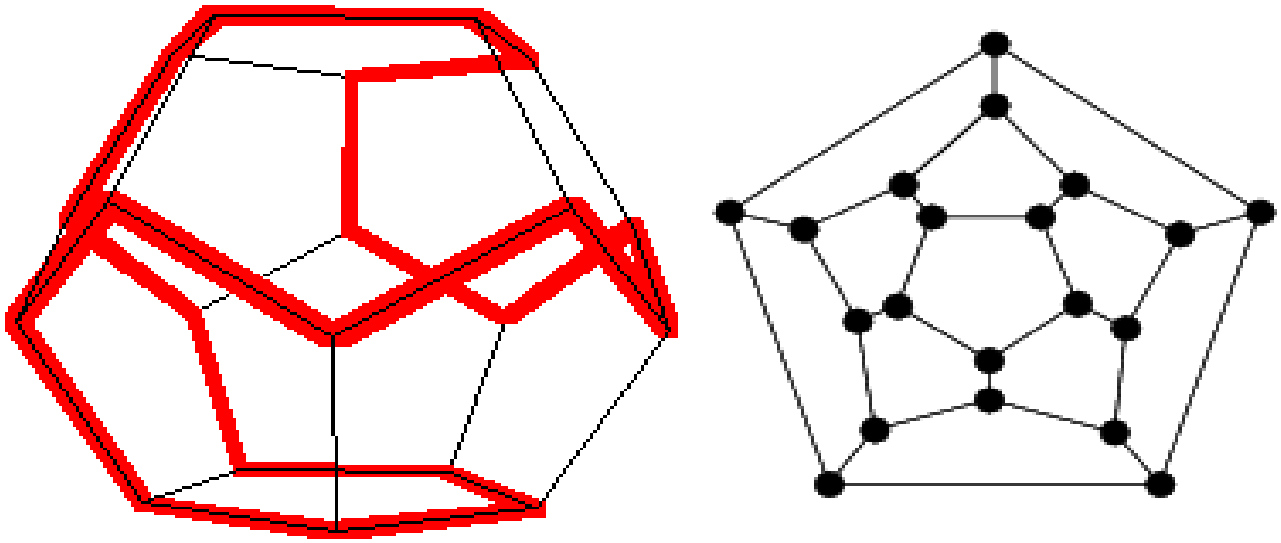
(a, e, c, d, e, b, a)

Hamilton Paths and Circuits

A *Hamilton path* in a graph G is a path which visits every vertex in G exactly once.

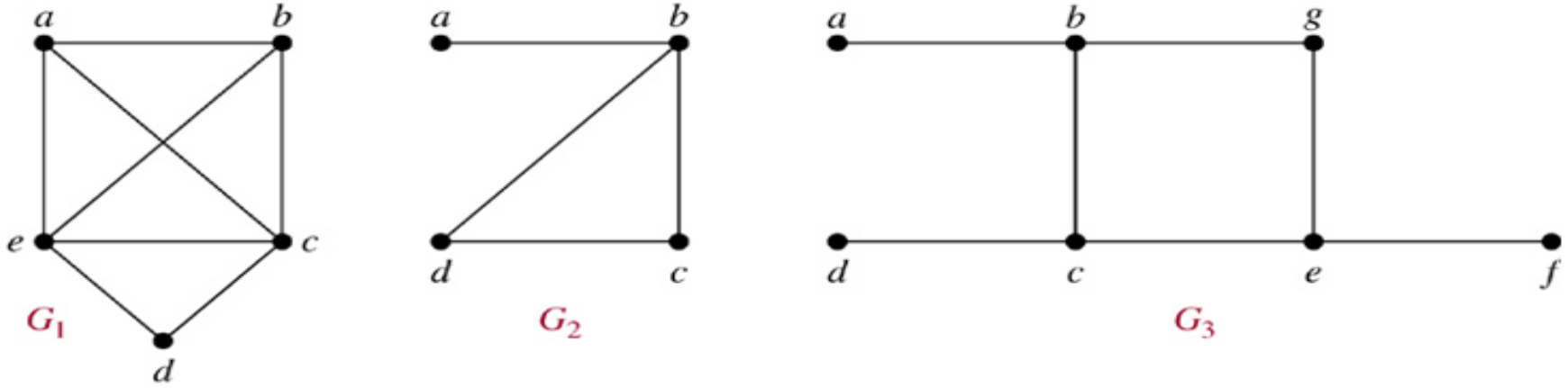
A *Hamilton circuit* is a Hamilton path that returns to its start.

Hamilton Circuits



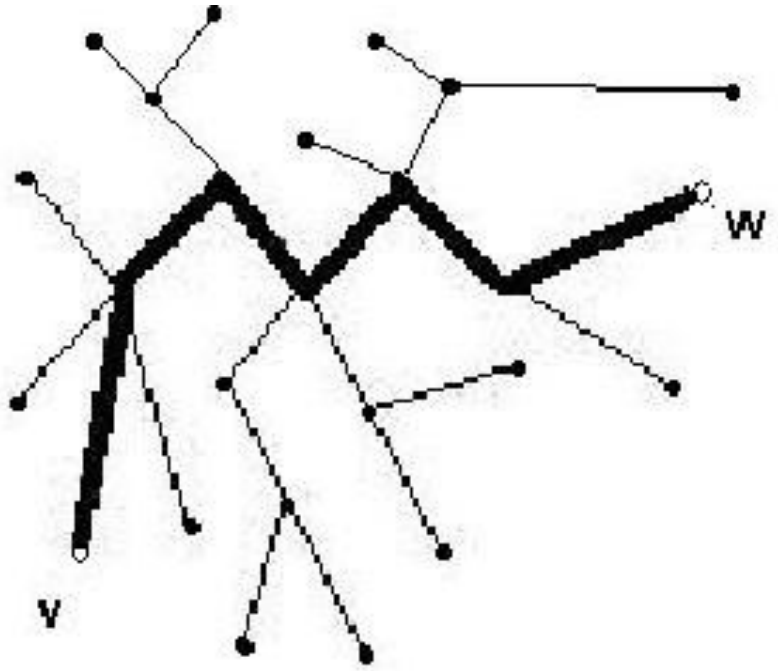
Dodecahedron puzzle and it equivalent graph

Example



- G_1 has a Hamilton circuit: a, b, c, d, e, a
- G_2 does not have a Hamilton circuit, but does have a Hamilton path: a, b, c, d
- G_3 has neither.

Tree



A tree T is

- A simple graph such that for every pair of vertices v and w
- there is a unique path from v to w

Terminology

Parent

Ancestor

Child

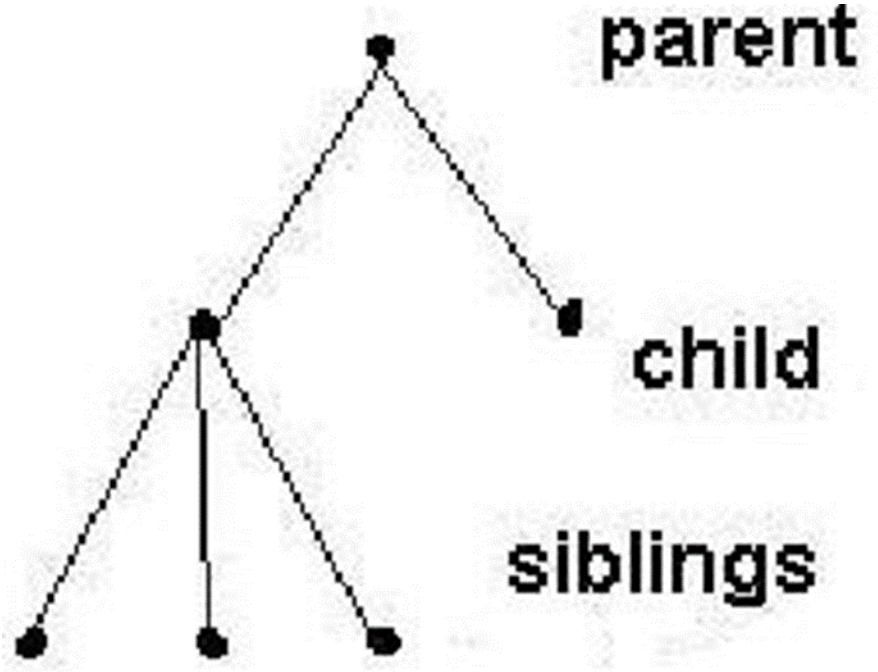
Descendant

Siblings

Terminal vertices

Internal vertices

Subtrees

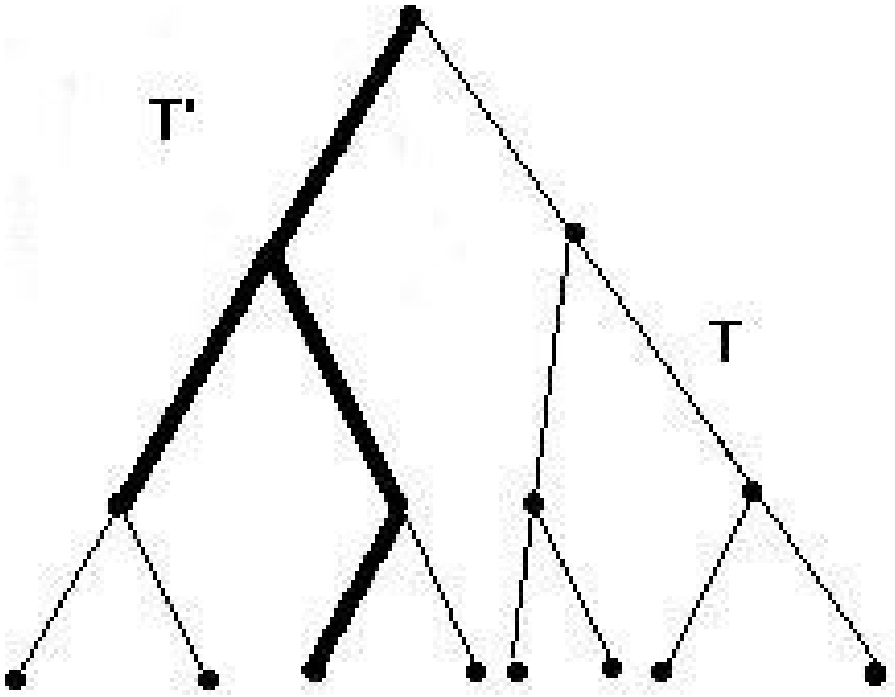


Subtrees

A subtree of a tree T is a tree T' such that

$V(T') \subseteq V(T)$ and

$E(T') \subseteq E(T)$



Properties of tree

If T is a graph with n vertices, the following are equivalent:

a) T is a tree

b) T is connected and acyclic

- ("acyclic" = having no cycles)

c) T is connected and has n-1 edges

d) T is acyclic and has n-1 edges

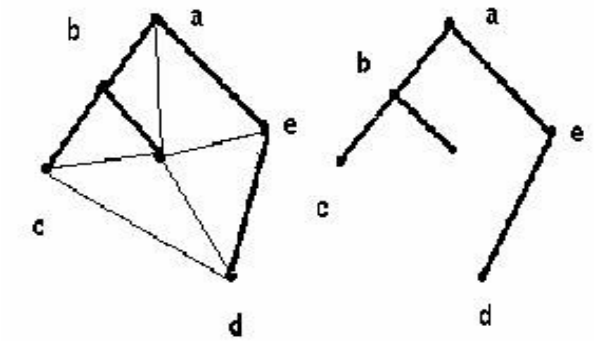
Spanning trees

Given a graph G, a tree T is a *spanning tree* of G if:

- T is a subgraph of G

  and

- T contains all the vertices of G



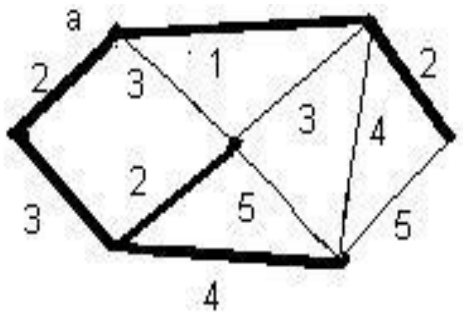
Prim's algorithm

Step 0: Pick any vertex as a starting vertex (call it *a*). T = {a}.

Step 1: Find the edge with smallest weight incident to *a*. Add it to T Also include in T the next vertex and call it *b*.

Step 2: Find the edge of smallest weight incident to either *a* or *b*. Include in T that edge and the next incident vertex. Call that vertex *c*.

Step 3: Repeat Step 2, choosing the edge of smallest weight that does not form a cycle until all vertices are in T. The resulting subgraph T is a minimum spanning tree.

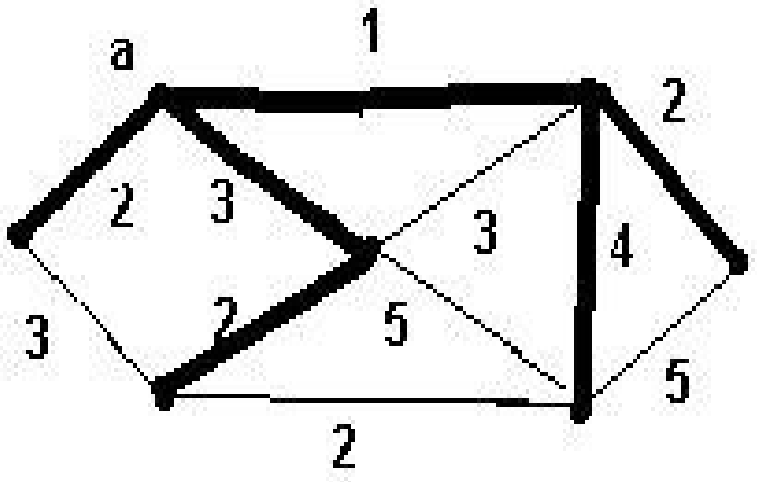


Kruskal's algorithm

Step 1: Find the edge in the graph with smallest weight (if there is more than one, pick one at random). Mark it with any given color, say red.

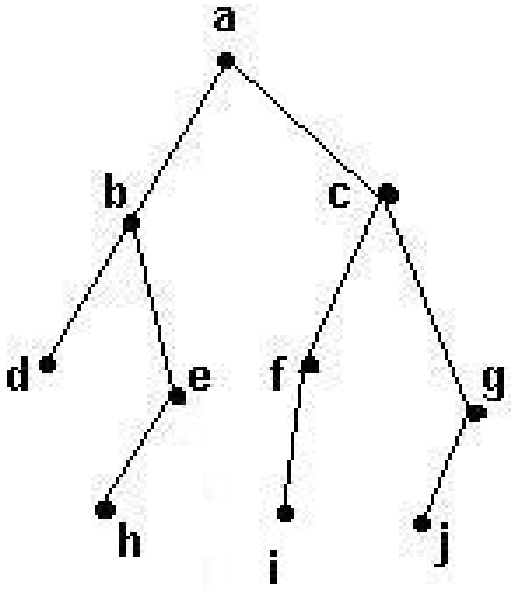
Step 2: Find the next edge in the graph with smallest weight that doesn't close a cycle. Color that edge and the next incident vertex.

- Step 3: Repeat Step 2 until you reach out to every vertex of the graph. The chosen edges form the desired minimum spanning tree.



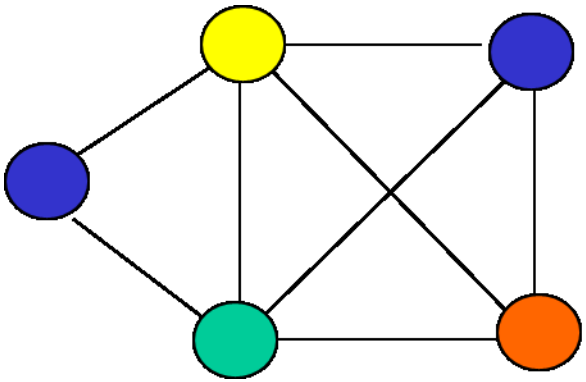
Binary trees

A *binary tree* is a tree where each vertex has zero, one or two children



Coloring Graphs

- **Definition**: A graph has been colored if a color has been assigned to each vertex in such a way that adjacent vertices have different colors.

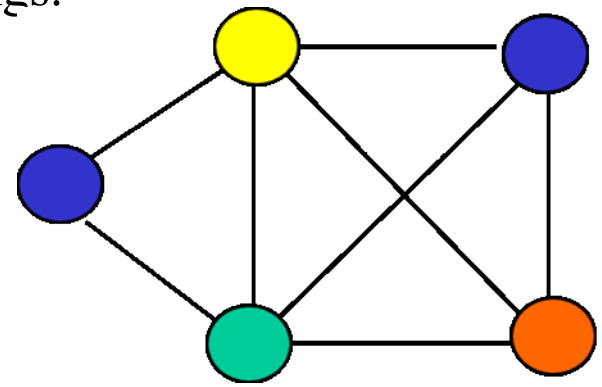


- **Definition:** The chromatic number of a graph is the smallest number of colors with which it can be colored.

  In the example above, the chromatic number is 4.

Coloring Planar Graphs

- **Definition**: A graph is planar if it can be drawn in a plane without edge-crossings.

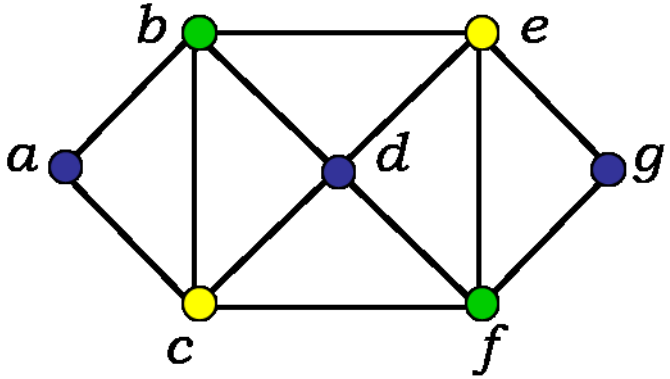


- **The four color theorem:** For every planar graph, the chromatic number is ≤ 4.

  Was posed as a conjecture in the 1850s. Finally proved in 1976 (Appel and Haken) by the aid of computers.

Example

What is the chromatic number of the graph shown below?



The chromatic number must be at least 3 since *a*, *b*, and *c* must be assigned different colors. So Let's try 3 colors first. 3 colors work, so the chromatic number of this graph is 3.

Game trees

Trees can be used to analyze all possible move sequences in a game:

Vertices are positions:

- a square represents one player and a circle represents another player

An edge represents a move

A path represents a sequence of moves

The End

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